

AS5001 (= SUPAAAA)
 ADA= "Advanced" (Astronomical) Data Analysis
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 ADA web page: <http://star-www.st-and.ac.uk/~kdh1/ada/ada.html>

All lecture pdfs, homework, projects, videos on Moodle.

Supplementary Texts:
 Press et al. (CUP) *Numerical Recipes : The Art of Scientific Computing*
 (on the web at [Numerical.Recipes](http://www.nr.com))
 Wall & Jenkins (CUP) *Practical Statistics for Astronomers*
 Gregory (CUP) *Bayesian Logical Data Analysis for the Physical Sciences*

Opinionated Lessons in Statistics, by Bill Press. [OpinionatedLessons.org](http://www.opinionatedlessons.org)

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ADA= "Advanced" (Astronomical) Data Analysis

Goal: Build concepts and skills for analysing quantitative data.

~15 Lectures: develop basic principles, illustrate with examples, extend step-by-step to build expertise for advanced analysis of datasets.
 50% 2 Homework sets: test understanding, build skills
 50% 2 Projects: analyse real datasets (Keck, HST)
NO EXAM :)

Work steadily, ask questions, get help when you don't understand, and you will succeed.

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ADA 01 - 10am Mon 12 Sep 2022

Astronomical Data + Noise
 Statistical vs Systematic errors
 Probability distributions (pdf, cdf)
 Mode, Mean, Median
 Variance, standard deviation, MAD
 Skewness, Kurtosis
 Parameterised distributions
 (Uniform, Gaussian, Lorentzian,
 Poisson, Exponential, Chi^2)

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ADA Lecture 1 Outline

- **Astronomical Data Sets**
- **Noise :**
 - statistical vs systematic errors
- **Probability distributions :**
 - Mean vs Median
 - Variance (standard deviation) vs MAD
 - Central moments (skewness, kurtosis)
- **Survey of parameterised distributions**
 - Uniform, Gaussian, Lorentzian, Poisson, Exponential, Chi-squared

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Astronomical Datasets

- (Almost) all our information about the Universe arrives as photons. (neutrinos, gravitational waves)
- **Photon properties:**
 - position: \vec{x}
 - time: t
 - direction: α, δ
 - energy: $E = h\nu = hc / \lambda$
 - polarisation: (Stokes parameters, $\vec{p} = I, Q, U, V$)
- Astronomical datasets are (usually) photon distributions confined by a detector to (some subset of) these properties:

$$D_i = \int P_i(\vec{x}, t, \alpha, \delta, \lambda, \vec{p}) f(\vec{x}, t, \alpha, \delta, \lambda, \vec{p}) d(\vec{x}, t, \alpha, \delta, \lambda, \vec{p}) + Noise_i$$

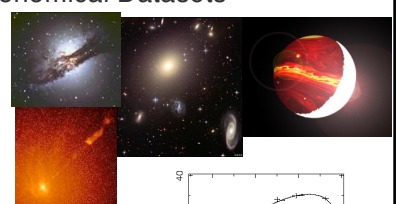
Photon detection probability for data point i	Photon distribution
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Astronomical Datasets

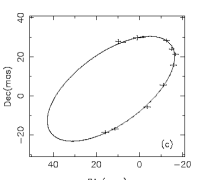
- **Direct imaging:**
 - size
 - structure

$D(\alpha, \delta)$



- **Astrometry:**
 - distance
 - parallax
 - motion
 - proper motion
 - visual binary orbits

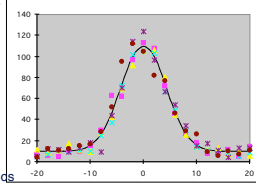
$D(\alpha, \delta, t)$



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Data are affected by Noise

- Repetitions of the same experiment or observation give different results.
- e.g. spectral-line profile:

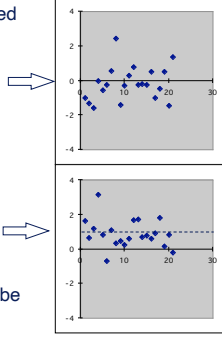


- Sources of noise:
 - **Quantum (Poisson) noise**
 - finite number of photons
 - **Thermal noise**
 - thermal fluctuations in the detector/electronics
 - **Rare events**
 - cosmic ray hits, instrument failures

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Data Values as "Random Variables"

- Consider an ensemble of repeated measurements.
- Data values "dance" around.

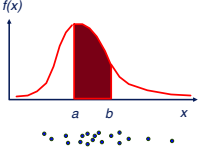


- **Statistical errors:**
 - From random nature of measurement process.
 - Can be reduced by averaging repeat measurements.
- **Systematic errors (bias):**
 - Due to flawed measurement technique.
 - Bias remains after averaging repeat measurements.
- **Probability distributions** describe this "dance" of the data values.

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Probability Distributions (PDFs)

- **Probability distribution $f(x)$**
- aka: *probability density function* (pdf)
- defines the probability that x lies in some range:

$$P(a < x \leq b) = \int_a^b f(x) dx$$


- **Probabilities add up to 1.**
- If x can take any value between $-\infty$ and $+\infty$ then

$$\int_{-\infty}^{\infty} f(x) dx = 1$$

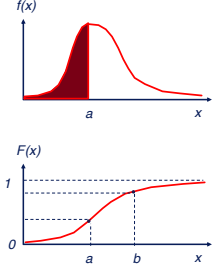
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Cumulative Probability Functions (CDFs)

- Integrating $f(x)$ gives the **cumulative probability** $F(a)$ that $x \leq a$:

$$F(a) = P(x \leq a) = \int_{-\infty}^a f(x) dx$$

$$F(-\infty) = 0 \quad F(+\infty) = 1$$

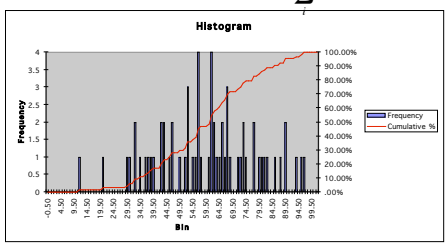
$$P(a < x \leq b) = \int_a^b f(x) dx = F(b) - F(a)$$


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Discrete Probability Distributions

- Example:
 - Exam marks
 - Photons per pixel

$$f(x) = \sum_i p_i \delta(x - x_i)$$

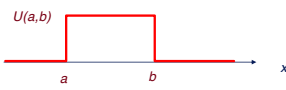
$$F(x) = \sum_i p_i \text{ for all } x_i \leq x$$


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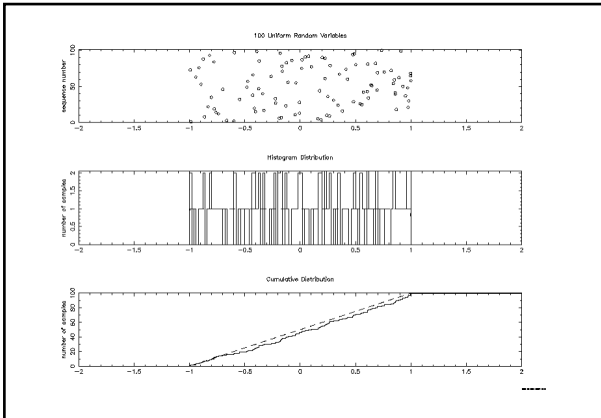
Uniform Distribution $U(a,b)$

- Also known as a "boxcar" or "tophat" distribution:

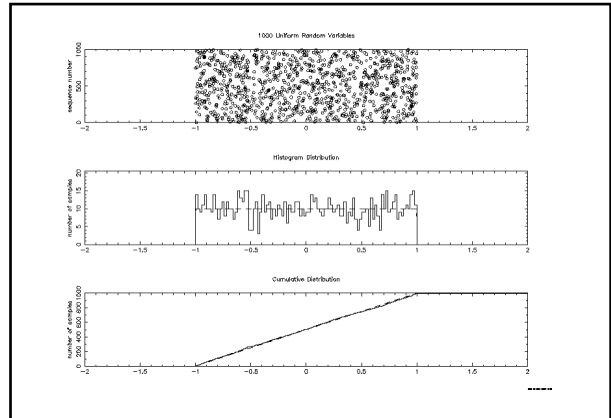
$$f(x) = \frac{1}{|b-a|} \text{ for } a < x < b$$

$$f(x) = 0 \text{ otherwise.}$$


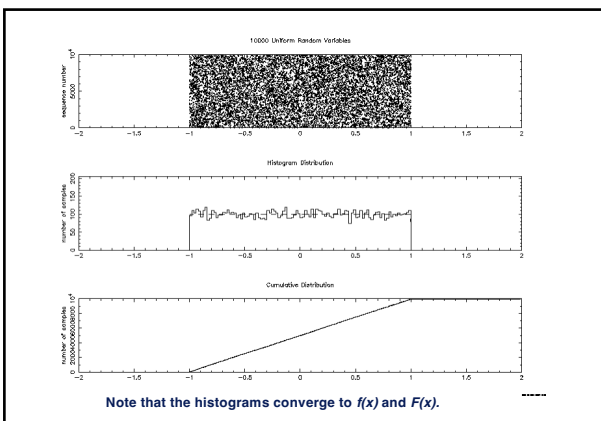
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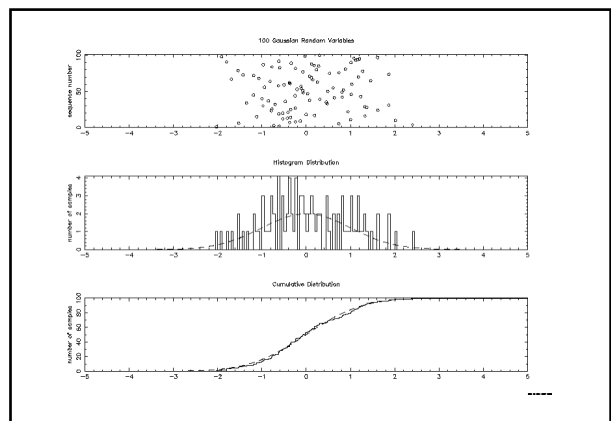
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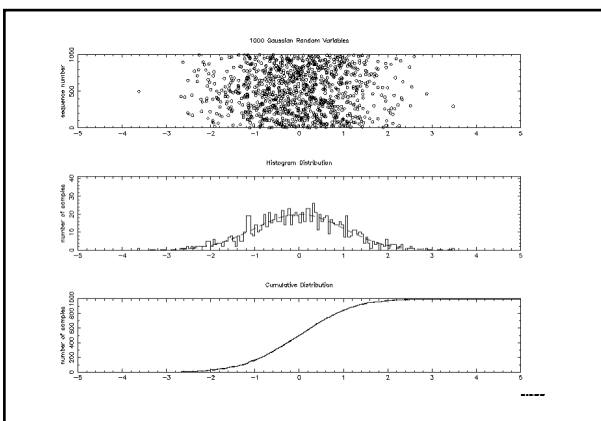
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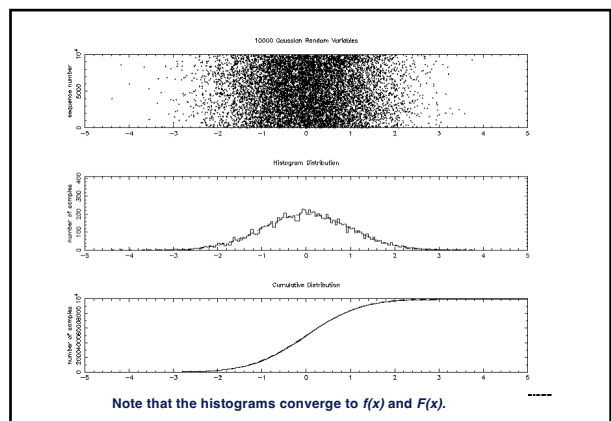
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Moments of Distributions

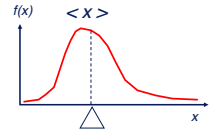
- The **moments** of a distribution characterise its **location, width and shape**.
- Strong physical analogy with moments in mechanics of rigid bodies:
 - Centre of mass = first moment
 - Moment of inertia = second (central) moment
 - Higher moments => info on the shape of the distribution

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Location measures: Mode, Mean and Median

- Mode** (highest probability density)
- Mean** (centre of mass)
= probability-weighted average of x

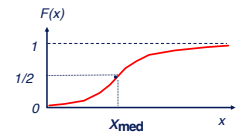
$$\langle x \rangle = \int f(x) x dx$$



- Median** (50th percentile)

$$F(x_{\text{med}}) = \frac{1}{2}$$

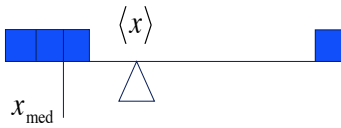
$$P(x < x_{\text{med}}) = P(x > x_{\text{med}})$$



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Mean vs Median

- Median** is less sensitive to the long wings of a distribution -- the outliers.



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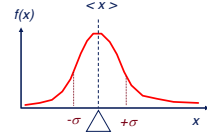
Width Measures: Standard Deviation, MAD

- Standard deviation σ** measures width of distribution.

$$\sigma^2(x) = \sigma_x^2 = \text{Var}(x) = \langle [x - \langle x \rangle]^2 \rangle = \int f(x) [x - \langle x \rangle]^2 dx$$

Mean Absolute Deviation (MAD):

$$\text{MAD} = \langle |x - x_{\text{med}}| \rangle$$



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Shape : Higher-order (Central) Moments

- General form: $m_n = \left\langle \left[\frac{x - \langle x \rangle}{\sigma} \right]^n \right\rangle$ (n^{th} central moment in units of σ^n)

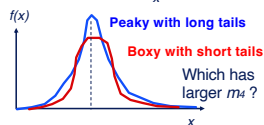
Higher central moments $n = 3, 4, \dots$ define the **shape** of the distribution.

- Skewness (m_3)**: (asymmetric tails)



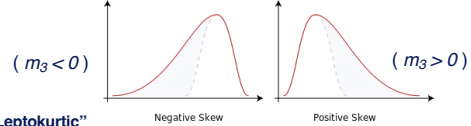
- Kurtosis (m_4)**:

If you know **all** the moments, you know the full shape.



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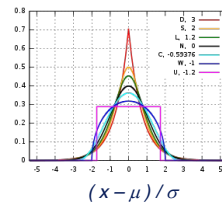
Skew and Kurtosis



"Leptokurtic" ($m_4 > 3$) with longer tails, like a kangaroo (leaps)

"Mesokurtic" ($m_4 = 3$) like a Gaussian.

"Platykurtic" ($m_4 < 3$) with shorter tails, like a platypus.



$m_4 > 3$ increases peak and wings relative to a Gaussian

Excess Kurtosis ($m_4 - 3$) defined relative to the kurtosis of a Gaussian.

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Gaussian Distribution $G(\mu, \sigma^2)$

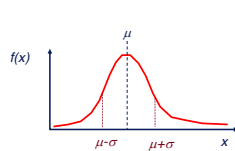
- Also known as a **Normal** distribution. $N(\mu, \sigma^2)$
- Physical example: thermal Doppler broadening

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2}$$

- 2 parameters:
- Mean (expected) value: $E(x) = \langle x \rangle = \mu$
- Variance: $\text{Var}(x) = \sigma^2(x) = \sigma^2$
- Standard deviation (dispersion) σ
- Full width at half maximum (FWHM)

$$\text{FWHM} = \sqrt{8 \ln 2} \sigma \approx 2.3\sigma$$

- 32% probability that x is outside $\mu \pm \sigma$
- 4.5% for x outside $\mu \pm 2\sigma$
- 0.3% for x outside $\mu \pm 3\sigma$



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Lorentzian (Cauchy) Distribution $L(\mu, \sigma)$

- Peak at $x = \mu$, $\text{HWHM} = \sigma$.
- Physical example: damping wings of spectral lines.

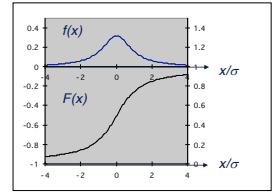
$$f(x) = \frac{\sigma}{\pi} \frac{1}{\sigma^2 + (x - \mu)^2}$$

$$F(x) = \frac{1}{\pi} \tan^{-1}\left(\frac{x - \mu}{\sigma}\right) + \frac{1}{2}$$

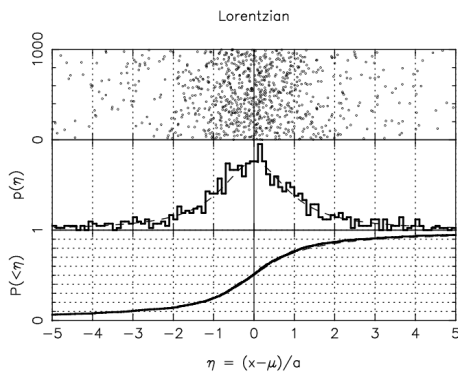
- Pathological: wings so broad that all moments diverge! ☹️

$$\langle x \rangle = \frac{\sigma}{\pi} \int_{-\infty}^{\infty} \frac{x dx}{\sigma^2 + (x - \mu)^2} \propto \ln|1 + x^2| \Big|_{-\infty}^{\infty} = \infty - \infty$$

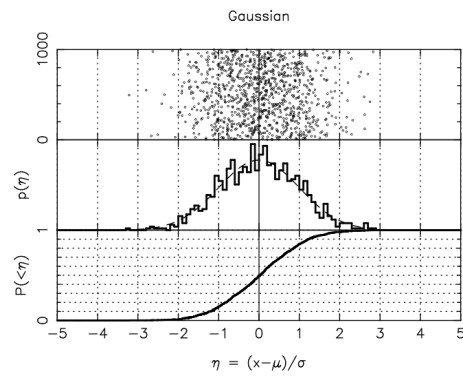
$$\langle (x - \mu)^2 \rangle = \infty$$



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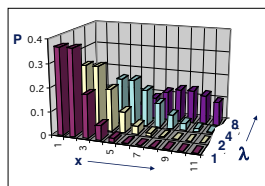
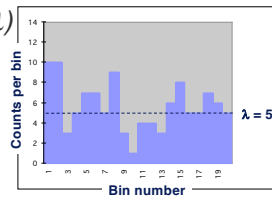
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Poisson Distribution $P(\lambda)$

- A discrete distribution
- Describes counting statistics:
 - Raindrops in bucket per time interval
 - Photons per pixel during exposure
- $\lambda = \text{mean count rate}$
 - Not necessarily an integer!



$$f(x) = \sum_{n=0}^{\infty} e^{-\lambda} \frac{\lambda^n}{n!} \delta(x - n)$$

$$P(x = n) = e^{-\lambda} \frac{\lambda^n}{n!} \quad n = 0, 1, 2, \dots$$

$$\langle x \rangle = \lambda$$

$$\sigma^2(x) = \lambda \Rightarrow \sigma(x) = \sqrt{\langle x \rangle}$$

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Exponential Distribution $E(\tau)$

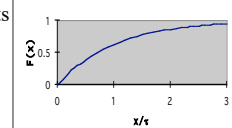
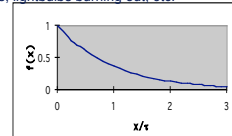
- Distribution of time intervals between random events
 - Raindrops, photons, radioactive decays, lightbulbs burning out, etc.

$$f(x) = \frac{1}{\tau} e^{-x/\tau}$$

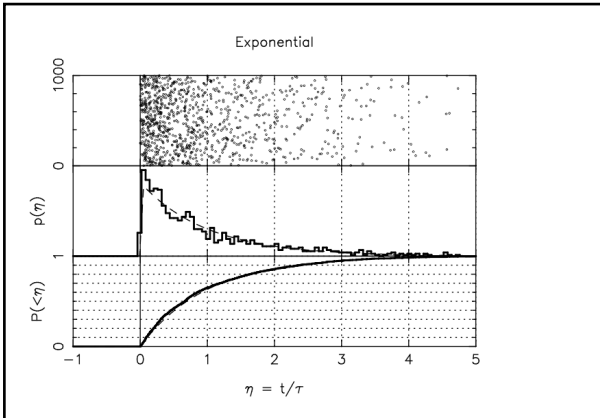
$$F(x) = 1 - e^{-x/\tau}$$

$$\langle x \rangle = \tau = \text{mean time between events}$$

$$\text{Var}[x] = \langle (x - \tau)^2 \rangle = \tau^2$$



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Chi-Squared Distribution χ^2_N

- Sum of squares of N independent Gaussian random variables

χ^2_N = Chi-Squared with N degrees of freedom

X and Y are independent Gaussian random variables.
 i.e. $X \sim G(0,1)$ $Y \sim G(0,1)$

then $X^2 \sim \chi^2_1$ $Y^2 \sim \chi^2_1$
 $X^2 + Y^2 \sim \chi^2_2$
 and so on for each new degree of freedom:
 $\chi^2_N + \chi^2_M \sim \chi^2_{N+M}$

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Chi-Squared = "Badness of Fit"

$$\chi^2 = \sum_{i=1}^N \left(\frac{D_i - \mu_i(\alpha)}{\sigma_i} \right)^2 \sim \chi^2_{N-P}$$

D_i = data value
 σ_i = $1 - \sigma$ error bar
 $\mu_i(\alpha)$ = model predicted data value
 α = parameters of the model

N = number of data points
 P = number of fitted parameters
 $N - P$ = degrees of freedom

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χ^2 distribution with N degrees of freedom

$$f(x) = \frac{1}{\Gamma(N/2) 2^{N/2}} x^{(N/2-1)} e^{-x/2}$$

$\Gamma(1) = 1$ $\Gamma(1/2) = \sqrt{\pi}$
 $\Gamma(n) = (n-1)!$ $\Gamma(x+1) = x \Gamma(x)$
 e.g. $\Gamma(3/2) = (1/2) \Gamma(1/2) = \sqrt{\pi}/2$

$\chi^2_1: f(x) = \left(\frac{e^{-x}}{2\pi x} \right)^{1/2}$
 $\chi^2_2: f(x) = \frac{1}{2} e^{-x/2}$

$\langle \chi^2_N \rangle = N$
 $\sigma^2(\chi^2_N) = 2N$

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χ^2_N and reduced χ^2_N distribution

- Sum of squares of N independent Gaussian random variables

Chi-squared with N degrees of freedom	Reduced χ^2_N
$\langle \chi^2_N \rangle = N$	$\left\langle \frac{\chi^2_N}{N} \right\rangle = 1$
$\sigma^2(\chi^2_N) = 2N$	$\sigma^2\left(\frac{\chi^2_N}{N}\right) = \frac{2}{N}$
$\sigma(\chi^2_N) = \sqrt{2N}$	$\sigma\left(\frac{\chi^2_N}{N}\right) = \sqrt{\frac{2}{N}}$

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