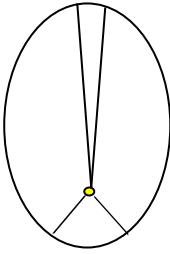


Kepler -- kinematics

- Empirical fit to Tycho Brahe's planet motion observations



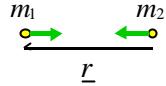
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- Kepler's laws:
 - Elliptical orbits Sun at focus
 - Equal areas in equal times
 - $P^2 \propto a^3$

Newton -- dynamics

$$\underline{F}_1 = -\underline{F}_2$$



$$\underline{F} = m \ddot{\underline{r}}$$

$$\underline{F}_1 = -\frac{G m_1 m_2}{r^2} \hat{\underline{r}}$$

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The N-body problem

$$\Phi(\underline{r}, t) = -\sum_{i=1}^N \frac{G m_i}{|\underline{r}-\underline{r}_i|} = \text{gravitational potential}$$

$$\underline{f} = -\nabla \Phi = \text{acceleration}$$

$$\text{equation of motion : } m \ddot{\underline{r}} = \underline{F} = m \underline{f} = -m \nabla \Phi$$

$$\underline{J} \equiv \underline{r} \times (m \dot{\underline{r}}) = \text{angular momentum}$$

$$\dot{\underline{J}} = \underline{r} \times (m \ddot{\underline{r}}) + \dot{\underline{r}} \times (m \dot{\underline{r}})$$

$$= \underline{r} \times \underline{F} \equiv \underline{G} = \text{torque}_o$$

Note: If $\underline{F} \parallel \underline{r}$ then $\underline{J} = \text{constant}$

and $\underline{r}, \dot{\underline{r}}$ (both $\perp \underline{J}$) define orbital plane.

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Energy of orbit

$$\text{Kinetic Energy : } K \equiv \frac{1}{2} m |\dot{\underline{r}}|^2 = \frac{1}{2} m (\dot{\underline{r}} \cdot \dot{\underline{r}})$$

$$\dot{\underline{K}} = m \dot{\underline{r}} \cdot \ddot{\underline{r}} = \dot{\underline{r}} \cdot \underline{F} = -m \dot{\underline{r}} \cdot \nabla \Phi$$

$$\text{Potential Energy : } W \equiv m \Phi$$

$$\dot{W} = m \dot{\Phi} + m \left(\frac{d\Phi}{dx} \frac{dx}{dt} + \frac{d\Phi}{dy} \frac{dy}{dt} + \frac{d\Phi}{dz} \frac{dz}{dt} \right)$$

$$= m \dot{\Phi} + m \nabla \Phi \cdot \dot{\underline{r}}$$

$$\text{Total Energy : } E = K + W$$

$$\dot{E} = \dot{K} + \dot{W} = (-m \dot{\underline{r}} \cdot \nabla \Phi) + (m \dot{\Phi} + m \nabla \Phi \cdot \dot{\underline{r}}) = m \dot{\Phi}$$

∴ Energy is constant if $\Phi = 0$

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Orbits in spherical potentials

If $\Phi(r)$ depends on $|\underline{r}|$, not \underline{r} , then

$$\underline{f} = -\nabla \Phi = -\frac{d\Phi}{dr} \hat{\underline{r}}$$

then

$$\dot{\underline{J}} = \underline{r} \times m \underline{f} = -m \frac{d\Phi}{dr} \underline{r} \times \hat{\underline{r}} = 0$$

→ angular momentum about origin is conserved !

∴ orbital motion is in a plane

$\underline{r}, \dot{\underline{r}}$ in plane,

specific angular momentum

$$\underline{L} \equiv \frac{\underline{J}}{m} \text{ perpendicular to plane}$$

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Kinematics

$$\text{position } \underline{r}(t)$$

$$\text{velocity } \dot{\underline{r}} = \dot{r} \hat{\underline{r}} + r \dot{\underline{q}} \hat{\underline{q}}$$

$$\text{speed } V = \sqrt{\dot{r}^2 + r^2 \dot{\underline{q}}^2}$$

unit vectors rotate with \underline{q} along the trajectory

$$\hat{\underline{r}} = \frac{d\hat{\underline{r}}}{dt} = \frac{d\hat{\underline{q}}}{d\underline{q}} \frac{d\underline{q}}{dt} = \hat{\underline{q}} \dot{\underline{q}}$$

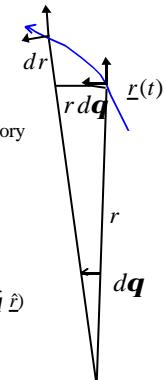
$$\hat{\underline{q}} = \frac{d\hat{\underline{q}}}{dt} = \frac{d\hat{\underline{q}}}{d\underline{q}} \frac{d\underline{q}}{dt} = -\hat{\underline{r}} \dot{\underline{q}}$$

acceleration

$$\ddot{\underline{r}} = \ddot{r} \hat{\underline{r}} + \dot{r} (\dot{\underline{q}} \hat{\underline{q}}) + \dot{r} \dot{\underline{q}} \hat{\underline{q}} + r \ddot{\underline{q}} \hat{\underline{q}} + r \dot{\underline{q}} (-\dot{\underline{q}} \hat{\underline{r}})$$

$$= (\ddot{r} - r \dot{\underline{q}}^2) \hat{\underline{r}} + (2 \dot{r} \dot{\underline{q}} + r \ddot{\underline{q}}) \hat{\underline{q}}$$

should be 0 if \underline{F} parallel to \underline{r}



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Kepler's 2nd Law

area swept out by \underline{r} in time t

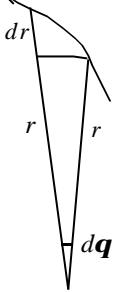
$$dA = \frac{1}{2} (r^2 d\dot{\theta} + r dr d\theta)$$

$$\dot{A} = \frac{1}{2} r^2 \dot{\theta}$$

$$= \frac{1}{2} \underline{r} \times \dot{\underline{r}} = \frac{J}{2m} = \text{constant}$$

$$\text{Note: } \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) = 2r \dot{\theta} + r \ddot{\theta} = 0$$

transverse component of acceleration = 0



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Conic Sections

$$r = \frac{\ell}{1 + e \cos \theta}$$

e = eccentricity

> 1 hyperbola

= 1 parabola

< 1 ellipse

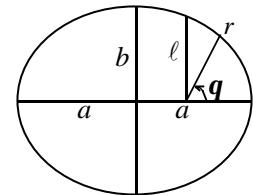
= 0 circle

ℓ = semi-latus rectum

a = semi-major axis

b = semi-minor axis

$$= a(1 - e^2)^{1/2}$$



$$\begin{aligned} \theta = 0 & \quad r = \frac{\ell}{1+e} = a(1-e) & \text{perihelion} \\ \theta = 90^\circ & \quad r = \ell = a(1-e^2) \\ \theta = 180^\circ & \quad r = \frac{\ell}{1-e} = a(1+e) & \text{aphelion} \end{aligned}$$

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